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Impact of Level-Converter on Power-Saving Capability of Clustered Voltage Scaling

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Abstract. The use of multiple supply voltages to reduce active mode power dissipation in digital ULSI circuits has been widely discussed in literature. As the reported power savings differ significantly depending on the technology and level converter circuits an abstract approach is used to investigate the impact of power consumption and delay caused by the level converters (what-if-scenarios). Actual circuits are used to map the theoretical investigations to real circuits. In contrast to clustered voltage scaling, where level conversion is only allowed in front of or within flipflops the power saving benefits of enhanced clustered voltage scaling with arbitrary converter positions vanish due to the lack of efficient asynchronous level converters.

1 Introduction

Power dissipation has become one of the main challenges in ULSI digital CMOS circuits. Moore's Law predicts a rapidly increasing number of devices and hence not only functionality of the respective chips but also the number of switching events per time rises rapidly. To manage dynamic power consumption the supply voltage has been decreased continuously. However, to fulfil the given speed requirements the transistor threshold voltage has been decreased, too. This results in exponentially growing subthreshold currents and static power consumption. Thus the supply and threshold voltage in circuits for low stand-by power consumption is not reduced as much as the supply voltage in high-performance circuits with low operating power requirements (ITRS, 2003).

The claimed growth of system size is only possible with agressive device scaling. This results not only in high area efficiency and fast switching behaviour but also in various parasitic effects. With respect to power consumption, drain induced barrier lowering (DIBL) and gate tunneling are the

most serious ones. To cope with the growing power consumption various low power strategies on circuit level have been proposed: If static power consumption is predominant and some circuit blocks of the whole System on Chip (SoC) are not used all the time it is beneficial to switch these circuit blocks temporarily off. This is done by the insertion of a sleep transistor between the circuit and the power supply (Mutoh, 1995; Kawaguchi, 1995; Min, 2003; Meer, 2003; Henzler, 2003; Tschanz, 2003, Henzler, to be presented, 2005¹). Sleep transistor technique is dedicated to leakage current reduction in stand-by mode. To reduce the power dissipation in active mode multi- V_{DD}/V_{th} schemes have been proposed. These techniques identify fractions of a given circuit which are faster than necessary. Power can be saved by reducing the speed of the respective gates while fulfilling the overall timing specification. Section 2 discusses clustered voltage scaling (CVS) which is a simple but efficient multi- V_{DD} technique. Section 3 discusses level converter circuits suitable for the CVS approach. A voltage assignment tool which can work with arbitrary assignment algorithms has been implemented. It is based on static timing analysis and detailed library characterization. By manipulating the characterization of the level converters it is possible to investigate "what-if-scenarios" for power and delay of the used converters. These scenarios are discussed in Sect. 4.

2 Clustered Voltage Scaling

The maximum clock frequency of a synchronous logic circuit is given by the D-to-Q delay of the flipflops including the setup time and the worst case delay of the critical logic path. In parallel to the critical path there exist other paths within the logic that show a smaller propagation delay. This

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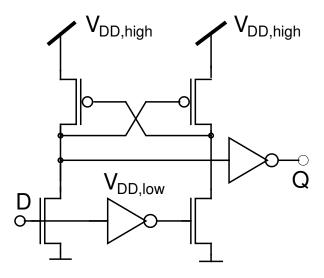


Fig. 1. Asynchronous standard level converter (differential cascode voltage switch architecture).

delay has to be long enough to not violate the flipflop hold time requirements. The time difference between the worst case propagation delay of the critical path and any other path of the circuit is called the timing slack of the respective path. The slack describes how much delay can be traded against power in the considered path. As the logic topology of most circuits is extremly interwoven, different paths cannot be optimized independently. Anyway, it is possible to slow down short paths by increasing the transistor threshold voltage, by gate resizing or by decreasing the supply voltage. Using high threshold logic gates is beneficial especially in low activity paths where leakage currents dominate. Subthreshold current decreases exponentially with growing threshold voltage but signal propagation delay increases. The delay can be estimated by using the well known alpha-power law [Sakurai (1990)]

$$t_d \approx \frac{V_{DD}}{\left(V_{DD} - V_{th}\right)^{\alpha}},\tag{1}$$

where the velocity saturation index α has a value between 1 and 2. Multiple-threshold logic requires additional threshold adjustment implantation during manufacturing but if available the technique is very advantageous as no interface circuitry between different threshold domains is required. Only a slight area penalty may occur if the minimum distance between devices of different threshold voltage is mentionable increased.

Reducing the supply voltage in short paths mainly results in quadratically decreased dynamic power dissipation but also in damped leakage currents: Subthreshold current is reduced due to Drain-Induced-Barrier-Lowering (DIBL) and gate tunneling current due to the exponential dependence on the voltage drop accross the barrier. The main drawback of multi- V_{DD} approaches is the necessity of level converters at the interface between the low and the high voltage domain.

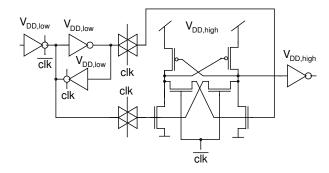


Fig. 2. Standard level converter flipflop including the asynchronous standard level shifter in the slave stage.

These circuits cause additional propagation delay in the signal path and consume additional energy. This overhead is mostly negligible if a block-level multi- V_{DD} technique is used with large coherent circuit blocks. However, if multiple supply voltages are used on gate level power and delay increments consume most of the timing slack available in the system. This means that a certain path has to be significantly shorter than the critical path to compensate for the additional delay of the level shifter circuit. Moreover the power dissipation within the converter has to be saved by the gates operating at $V_{DD,low}$ before the total power dissipation can be reduced at all. With respect to switching activity multi- V_{DD} techniques would be beneficual especially in data-path logic. However, the maximum number of subsequent gates in one pipeline stage has been dramatically reduced during the last years and architectures have been highly parallelized. Hence there is a very narrow design window concerning power consumption and delay of level shifters to be used for gate-level multi- V_{DD} techniques. Anyway, even with excellent level converters highly parallel datapath structures e.g. parallel prefix adders do not enable much power reduction. Circuits with a widespread path delay distribution are much more suitable even if the average switching activity is mostly lower.

It has been shown that an integration of the level conversion task within a flipflop can be beneficial with respect to power and delay increment. A gate level multi- V_{DD} technique is called clustered voltage scaling (CVS) if gates of the same supply voltage are grouped together and if the group supplied by $V_{DD,low}$ is located directly in front of the flipflops. Thus a $V_{DD,high} \rightarrow V_{DD,low}$ transition can occur anywhere within the logic as no level converters are required. However, the reverse transition is only possible in front or within the flipflops. Extended clustered voltage scaling (ECVS) allows the $V_{DD,low} \rightarrow V_{DD,high}$ transition at arbitrary positions in the logic. Hence in contrast to CVS the maximum number and the position of the level shifters is not clearly defined. Voltage assignment algorithms for ECVS are more flexible but also more complex than algorithms for CVS. The latter ones can be implemented easily and differ mainly in the way they generate additional slack by gate resizing.

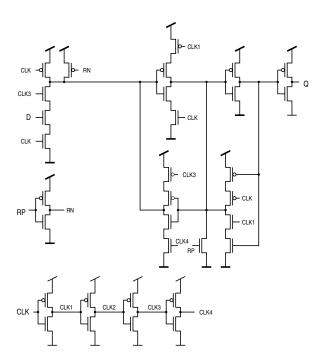


Fig. 3. Semi-dynamic level converter flipflop in master-slave architecture. A logic decision node in the master stage is precharged during the low phase of the clock and conditionally discharged during an evaluation period triggered by the rising clock edge.

3 Level-Converter Circuits

The first and most common approach to level conversion is the Differential Cascode Voltage Switch (DCVS) circuit shown in Fig. 1. The input signal D out of the $V_{DD,low}$ domain is inverted by an inverter which is supplied by $V_{DD\ low}$. To avoid short circuit currents the signals D and \overline{D} drive only n-channel pull-down devices. The logic high signal at the $V_{DD,high}$ level is generated by the feedback structure. The major drawback of this level converter circuit is the fact that both supply voltages are used within the level converter cell. As the contention between the PMOS feedback circuitry and the NMOS pull-down transistor becomes stronger with decreasing NMOS overdrive, the delay of the circuit becomes a strong function of input voltage level. Hence a detailed characterisation of a converter standard cell becomes challenging. Clustered voltage scaling performs level conversion only in front of the flip-flops. Thus the integration of levelconversion into a flip-flop circuit is straight forward. Figure 2 shows one realization of a level converter flip-flop which is based on the previously described level converter circuit of Fig. 1. As the $V_{DD,low}$ dependent contention is still existent in the slave the delay and power penalty of level conversion is a noticeable fraction of the flip-flops's total delay and power consumption. An alternative static approach (Mahmoodi, 2002) uses a self-precharge structure to generate the high output level but still needs both supply voltages within the flip-flop cell. A semi-dynamic level converter flip-flop

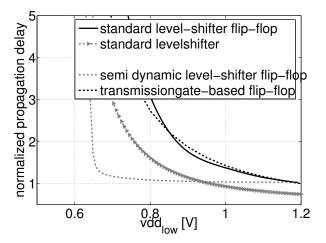


Fig. 4. Comparison of signal propagation delay of the level shifters in dependence of the lower supply voltage.

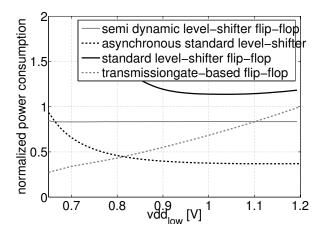


Fig. 5. Comparison of the power dissipation of the level shifters in dependence of the lower supply voltage.

(Henzler, 2004) is shown in Fig. 3. It still consists of the classical master-slave structure. The master has one dynamic node which is precharged during the low phase of the clock signal. On the rising clock edge a short pulse sensitizes the evaluation path which allows an input dependent conditional discharge of the dynamic node. After the evaluation pulse feedback is activated and protects the charge on the dynamic node. Hence the circuit behaves dynamically only when the evaluation pulse is active. Afterwards the circuit is fully static again and allows robust and reliable operation even at very low frequencies.

Figure 4 shows the dependence of clock-to-Q delay on the lower supply voltage. The delay of the asynchronous level converter is relatively small at heigh values of $V_{DD,low}$ but increases rapidly with decreasing input voltage. The classical level converter flip-flop shows nearly the same delay dependence as the asynchronous converter. As only

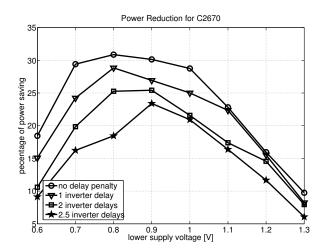


Fig. 6. What-If-Scenario where the level shifter is assumed to have no power penalty but varying propagation delay. The power saving capability of the C2670 benchmark circuit vanishes rapidly with increasing converter delay.

 $V_{DD,high}$ is used within the semi-dynamic level converter the delay variation with $V_{DD,low}$ is very small which is beneficial for the efficiency and flexibility of multi- V_{DD} techniques. The standard transmission gate based flip-flop without level-conversion functionality is shown as reference. Figure 5 demonstrates the dynamic power dissipation of the mentioned circuits. Dynamic power consumtion of the transmission-gate based flip-flop decreases quadratically with decreasing supply voltage. The single supply voltage and contention-free design of the semi-dynamic level converter keeps the power consumption constant, whereas in the classical approaches dynamic power becomes strongly dependent on $V_{DD,low}$. This results from the contention between feedback and pull-down path which becomes stronger with vanishing overdrive of the pull-down devices. It should be mentioned that alternative asynchronous level converters with pass gate based operation principle have been proposed. As these converters are normally not integrated in flipflops they are not regarded in this context. A drawback of these converters occurs if the voltage domains change dynamically. This is not the case in CVS and ECVS but may happen in block level multi- V_{DD} approaches where the different blocks can be reconfigured dynamically for changing application and performance requirements. A $V_{DD,high}$ level at the input of the standard pass-gate based level converter causes a cross current from the $V_{DD,high}$ input to the $V_{DD,low}$ supply.

4 Impact of Level-Converter on Total Power Reduction

The scope of this exploration is the description of the influence of the level converter on the effectiveness of multi- V_{DD} techniques. We do not intend to optimize the assignment algorithms with respect to their slack generation capability

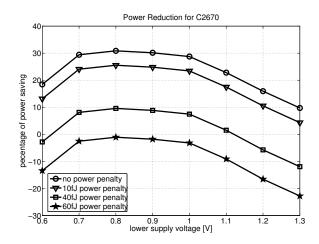


Fig. 7. What-If-Scenario where the level shifter is assumed to have no propagation delay but a varying power penalty. The power saving capability vanishes rapidly with increasing power consumption in the converter.

here. Conventional design tools try to reduce dynamic power and glitching probability by a proper sizing of the gates while correct timing is assured. This procedure shifts the path delay distribution towards the critical path which means reduction of timing slack. Hence sophisticated voltage assignment algorithms re-create this timing slack by resizing the gates again. Another approach performs these two tasks in one single design step where basic gate sizing and supply voltage assignment is done in parallel. To avoid a result dependence from a certain assignment algorithm we do not use gate resizing in this approach but therefore no aggressive slack consuming power optimization in a prior step. Hence netlists with a representative path delay distribution are used. In a static timing based foreward propagation step the worst case arrival times at each node are calculated. In the following backwards processing step the worst case arrival times plus the worst case gate delays are compared to the latest possible arrival time allowed by circuit's timing restrictions. Level converter delay and power penalty is considered if one of the succeeding gates is operated at the high supply voltage. If the remaining effective slack is positive the respective gate is assigned to the lower supply voltage. The influence on the dynamic and static power consumption is estimated by using a detailed gate characterization in combination with the state and switching probabilities of each gate.

In a first scenario the influence of level converter delay has been examined. Therefore it is assumed that the level converter has no power penalty. The propagation delay has been varried in multiples of an inverter delay in the considered technology and with the required drive strength. Figure 6 shows the relative power saving for ISCAS C2670 benchmark circuit in dependence of the lower supply voltage. With decreasing supply voltage $V_{DD,low}$ the power saving increases due to quadratic impact on energy dissipation.

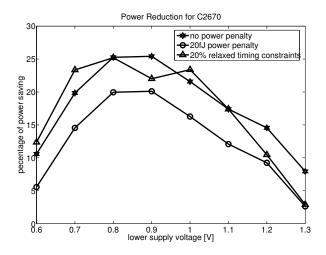


Fig. 8. C2670 benchmark circuit with relaxed timing: A 20% relaxed timing specification is necessary to compensate for a 20 f J power penalty in the level converters.

As the gate delay grows in parralel, the number of gates assigned to the lower supply voltage is reduced with decreasing $V_{DD,low}$. Hence, there is a maximum power saving and an appropriate optimum value of $V_{DD,low}$. It can be seen that the power saving drops significantly even with small delays assumed for the level converter. Thus a fast level shifter design is essential for exploiting the power saving capability of a given circuit.

Figure 7 shows the results of a second scenario where the level converter is assumed to cause only a power penalty. The power saving vanishes rapidly with increasing power consumption in the level shifter. Whatever $V_{DD,low}$ is choosen no power will be saved at all if a power penalty of 60 f F is assumed. The graph also shows the necessity for a post processing step which checks the effectiveness of each single level converter. If the power saving in the low- V_{DD} fan-in path of the level converter is lower than the energy overhead the converter will be removed and the respective gates connected to $V_{DD,high}$ again. For better demonstration of power penalty this step has been disabled to generate the graph in Fig. 7. Otherwise negative parts of the curves would be pinned to the zero percent value.

Relaxed Timing constraints can help to increase efficiency of the multi V_{DD} scheme. Figure 8 shows that for the demonstration circuit a 20% relaxed timing is necessary to compensate for a $20 \, f \, J$ power penalty of the level shifter. This emphasizes the importance of low-power converter circuits for the efficiency of multi- V_{DD} schemes.

One drawback of CVS is the fact that due to reconvergence short paths in the front part of the logic interacting with any critical path cannot be supplied by the lower supply voltage. Extended clustered voltage scaling circumvents this drawback by allowing asynchronous level shifters at arbitrary positions within the logic. However, asynchronous level

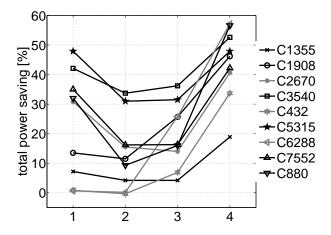


Fig. 9. Power saving potential of benchmark circuits:

- 1: semi-dynamic level converter flipflop
- 2: conventional level converter flipflop
- 3: ECVS with conventional asynchronous level converter within the logic
- 4: ECVS without power and delay penalty due to asynchronous level conversion (artificial).

converters are often slower and consume more power than their synchronous counterparts integrated in flipflops. Thus the power saving by reducing the voltage in these paths is usually much smaller compared to low V_{DD} paths ending at the flipflops. Figure 9 shows the maximum power saving potential of some benchmark circuits. Position 1 and 2 compare the results of CVS for the semi-dynamic level converter flipflop and the conventional converter flipflop. It can be seen that the fast energy efficient semi-dynamic level shifter flipflop gains considerably better results than the conventional approach. At position 4 the maximum power saving potential for ECVS is shown where it has been assumed that the asynchronous level converters contribute neither power nor delay penalties. Using the conventional asynchronous converter reduces the power saving significantly. In many cases almost no further reduction with respect to CVS can be observed. Following in many circuits, without effective asynchronous level converters ECVS has minor advantages over CVS. In Kulkarni (2004)] alternative asynchronous LC realizations have been discussed. However, these converters still suffer from power and delay penalties noticeable in voltage assignment algorithms. Hence the slack in paths not ending directly in front of a flipflop can be used more efficiently to reduce leakage power by using high threshold devices and reduced transistor widths.

If a certain single stage gate is supplied by $V_{DD,low}$ instead of $V_{DD,high}$ the power dissipation is reduced by

$$\Delta P_D = \alpha f C \left(V_{DD,high}^2 - V_{DD,low}^2 \right) + \mathbf{p}_z^T \cdot \left(\mathbf{P}_{leak,high} - \mathbf{P}_{leak,low} \right) - pp,$$
 (2)

where short circuit currents have been neglected. The switching activity α can be calculated if the logic topology and

the input statistic is known. C describes the average load capacitance consisting of the external load plus the medium internal capacitance averaged over all transistions. The second term describes the leakage power reduction caused by the reduced supply voltage. Therefore the state probability $\mathbf{p}_z = (p_{0...0}, p_{0...01}, \ldots, p_{1...1})^T$ of the input signals of the gate is multiplied by the leakage power reduction vector

The power penalty pp is a fraction of the total power consumption of the level converters distributed over all $V_{DD,low}$ gates. If the respective gate is realized using high threshold devices and supplied by $V_{DD,high}$ the power dissipation is reduced by

$$\Delta P_L = V_{DD,high} \mathbf{p}_z^T \Delta \mathbf{I}_{leak,vth} . \tag{4}$$

The vector

 $\Delta \mathbf{I}_{leak,vth}$

$$= \begin{pmatrix} V_{dd,high}I_{leak}^{0...0}(V_{th,low}) - V_{dd,high}I_{leak}^{0...0}(V_{th,high}) \\ \dots \\ V_{dd,high}I_{leak}^{1...1}(V_{th,low}) - V_{dd,high}I_{leak}^{1...1}(V_{th,high}) \end{pmatrix}$$
(5)

describes the leakage power reduction due to the higher treshold voltage and can be computed by analog simulation of the gate. Equating these two power reductions yields in the switching activity

$$\alpha > \mathbf{p}_{z}^{T} \frac{V_{DD,high} \Delta \mathbf{I}_{leak,vth} - \left(\mathbf{P}_{leak,high} - \mathbf{P}_{leak,low}\right) + pp}{fC\left(V_{DD,high}^{2} - V_{DD,low}^{2}\right)} \tag{6}$$

that has to be exceeded for multi- V_{dd} to be more effective than multi- V_{th} . Of course this estimation is only valid for a single gate and it has been assumed that both strategies cause less delay increment than the available slack. Anyway, it supports the decision for or against multi- V_{DD} by decribing the influence of device properties. If the load capacitance decreases e.g. by scaling or by the introduction of a low- κ dielectric in the backend the efficiency of various supply voltages decreases. A high system frequency and a widespread path delay distribution so that a very small second supply voltage can be used increases the multi- V_{DD} benefits. If leakage currents dominate the total power dissipation the use of different devices can be more beneficial than a second supply voltage: For instance a high threshold device is very beneficial in a subthreshold leakage dominated technology. However a lower supply voltage also impacts leakage currents especially if strong gate tunneling and DIBL occur. Thus the efficiency of multi- V_{DD} not only depends on the logic topology but also on the transistor technology. Unfortunately the decision between multi- V_{DD} and multi- V_{th} is more difficult on circuit level because due to level converters the decision for one gate influences the decision for other gates.

5 Conclusion

A voltage assignment tool has been applied to investigate the influence of signal propagation delay and power dissipation caused by level shifter circuits. Therefore "what-if-scenarios" have been used to demonstrate the effect on benchmark circuits. The power saving potential depends seriously on the the delay and power consumption of the level converters especially as timing slack is rare in many real-life circuits like datapath structures. Level converter circuits suitable for CVS have been discussed and their influence on the power saving in benchmark circuits has been demonstrated. The semi-dynamic level converter flipflop enables considerably higher power saving compared to the conventional converter flipflop. In theory (no penalties) ECVS allows better results than CVS but due to the lack of fast power efficient asynchronous level shifter circuits most of the power savings is consumed in the converters. Hence we discussed the use of multi- V_{th} strategies in paths not ending at the flipflops where efficient level conversion is possible. Anyway, the efficiency of both approaches is highly dependent on technology and circuit topology. Thus a combined scheme adapted individually to a given circuit for a given technology seems to be most beneficial.

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